



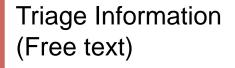
Today

- Decision Trees
- Tree construction
- Overfitting
- Pruning
- Real-valued inputs

Machine Learning in the ER

Physician documentation **Triage Information** Specialist consults (Free text) MD comments (free text) 2 hrs 30 min T=0Repeated vital signs Disposition (continuous values) Measured every 30 s Lab results (Continuous valued)

Can we predict infection?



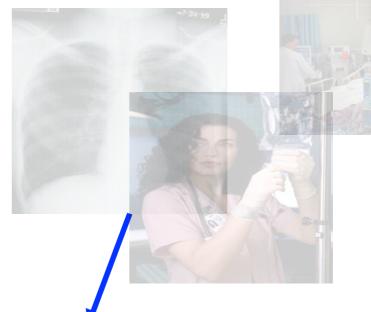


MD comments (free text)



Physician documentation





Many crucial decisions about a patient's care are made here!

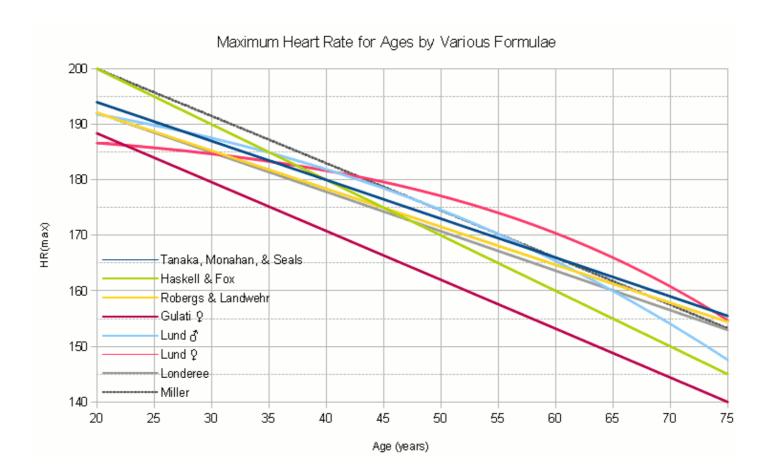


Repeated vital signs (continuous values)
Measured every 30 s

Men Men

Can we predict infection

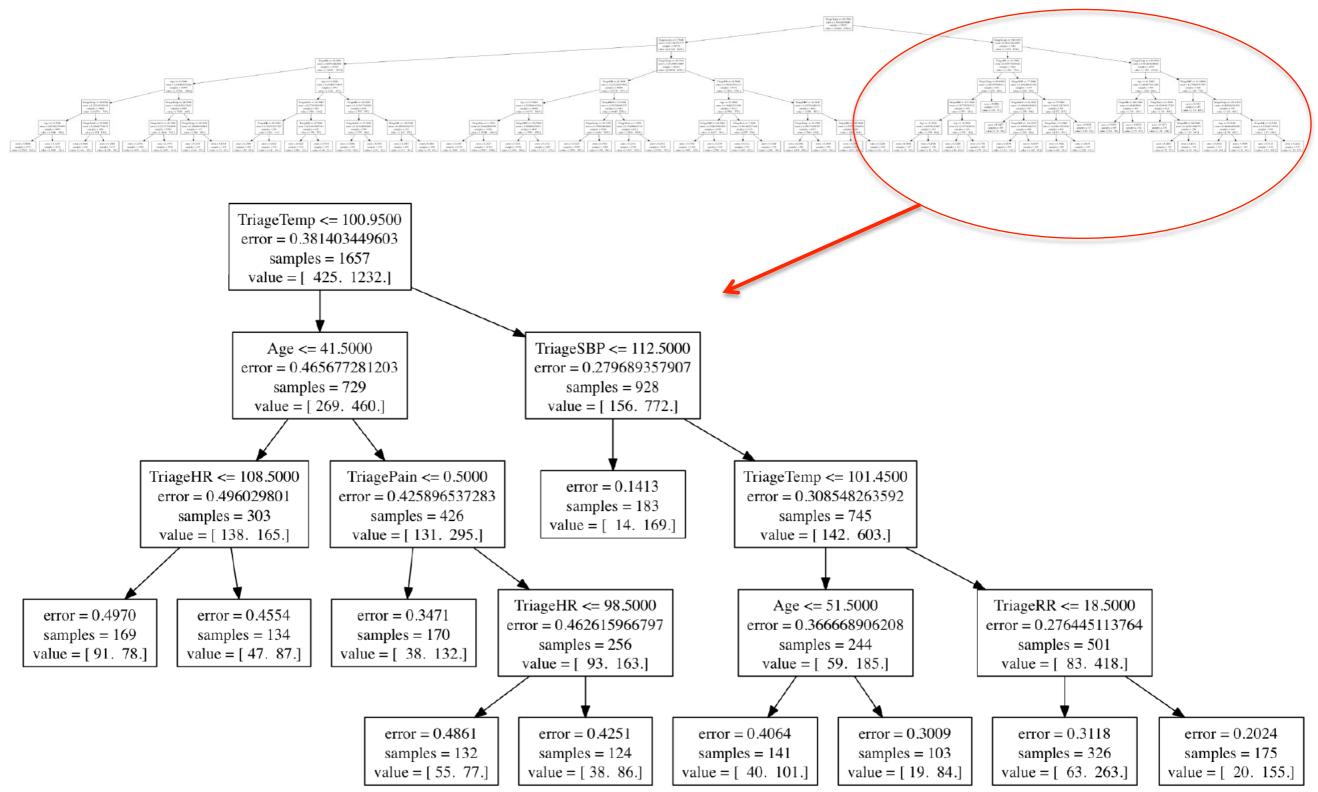
- Previous automatic approaches based on simple criteria:
 - Temperature < 96.8 °F or > 100.4 °F
 - Heart rate > 90 beats/min
 - Respiratory rate > 20 breaths/min
- Too simplified... e.g., heart rate depends on age!



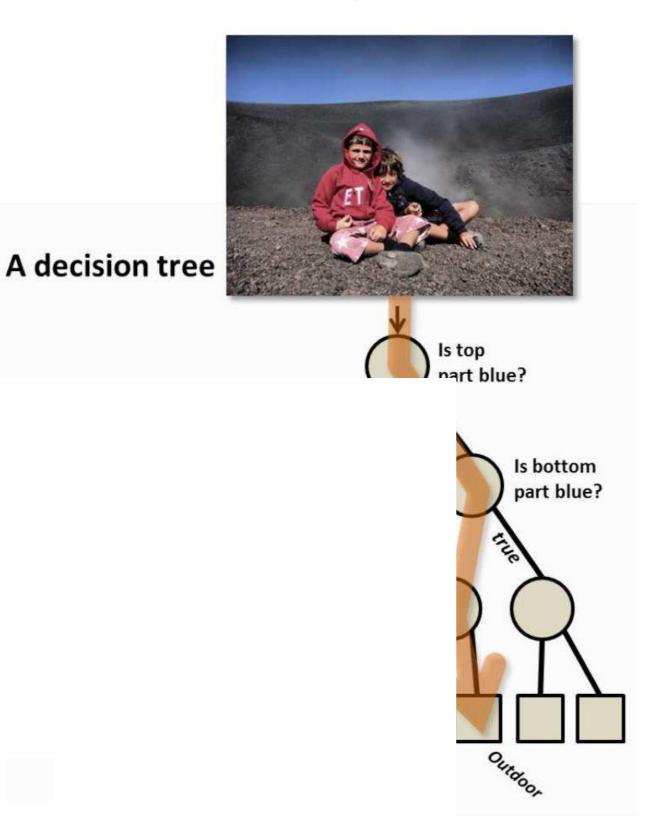
Can we predict infection?

- These are the attributes we have for each patient:
 - Temperature
 - Heart rate (HR)
 - Respiratory rate (RR)
 - Age
 - Acuity and pain level
 - Diastolic and systolic blood pressure (DBP, SBP)
 - Oxygen Saturation (SaO2)
- We have these attributes + label (infection) for 200,000 patients!
- Let's learn to classify infection

Predicting infection using decision trees



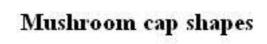
Example: Image Classification



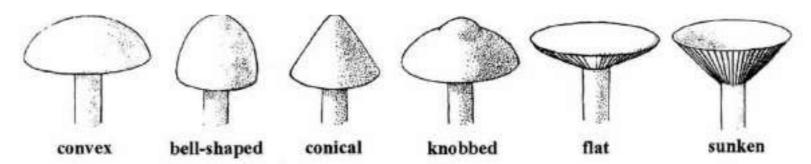
slide by Nando de Freitas

i et al, 2011]

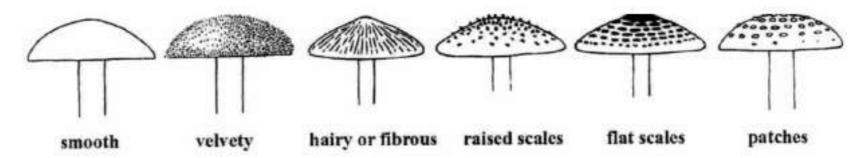
Example: Mushrooms



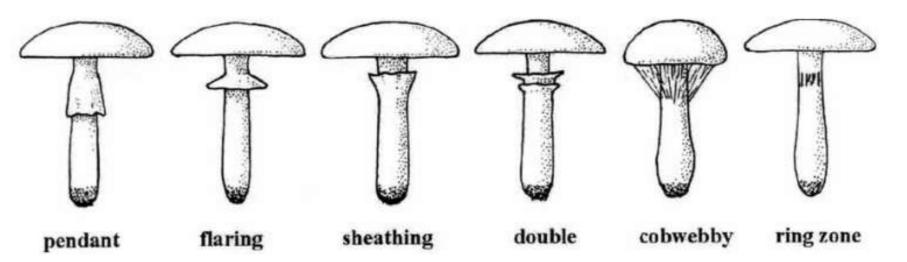




Mushroom cap surfaces



Annular rings



Mushroom features

- cap-shape: bell=b, conical=c, convex=x, flat=f, knobbed=k, sunken=s
- 2. cap-surface: fibrous=f, grooves=g, scaly=y, smooth=s
- 3. **cap-color:** brown=n, buff=b, cinnamon=c, gray=g, green=r, pink=p,purple=u, red=e, white=w, yellow=y
- 4. **bruises?:** bruises=t,no=f
- 5. **odor:** almond=a, anise=l, creosote=c, fishy=y, foul=f, musty=m, none=n, pungent=p, spicy=s
- 6. **gill-attachment:** attached=a, descending=d, free=f, notched=n
- */*

Two mushrooms

```
x_1=x,s,n,t,p,f,c,n,k,e,e,s,s,w,w,p,w,o,p,k,s,u

y_1=p

x_2=x,s,y,t,a,f,c,b,k,e,c,s,s,w,w,p,w,o,p,n,n,g

y_2=e
```

- cap-shape: bell=b,conical=c,convex=x,flat=f, knobbed=k,sunken=s
- 2. cap-surface: fibrous=f,grooves=g,scaly=y,smooth=s
- cap-color: brown=n,buff=b,cinnamon=c,gray=g,green=r, pink=p,purple=u,red=e,white=w,yellow=y
- 4. ...

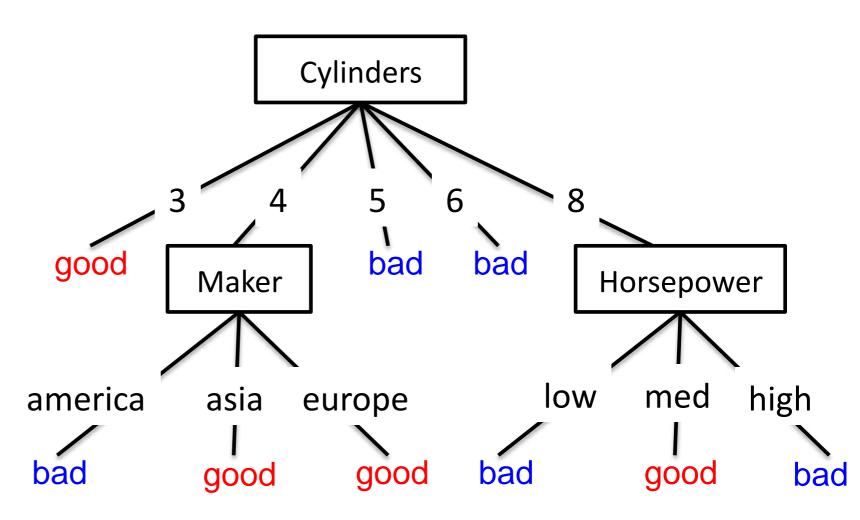
Example: Automobile Miles-pergallon prediction



| mpg | cylinders | displacement | horsepower | weight | acceleration | modelyear | maker |
|------|-----------|--------------|------------|--------|--------------|-----------|---------|
| | | | | | | | |
| good | 4 | low | low | low | high | 75to78 | asia |
| bad | 6 | medium | medium | medium | medium | 70to74 | america |
| bad | 4 | medium | medium | medium | low | 75to78 | europe |
| bad | 8 | high | high | high | low | 70to74 | america |
| bad | 6 | medium | medium | medium | medium | 70to74 | america |
| bad | 4 | low | medium | low | medium | 70to74 | asia |
| bad | 4 | low | medium | low | low | 70to74 | asia |
| bad | 8 | high | high | high | low | 75to78 | america |
| : | : | : | : | : | : | : | : |
| : | : | : | : | : | : | : | : |
| : | : | : | : | : | : | | : |
| bad | 8 | high | high | high | low | 70to74 | america |
| good | 8 | high | medium | high | high | 79to83 | america |
| bad | 8 | high | high | high | low | 75to78 | america |
| good | 4 | low | low | low | low | 79to83 | america |
| bad | 6 | medium | medium | medium | high | 75to78 | america |
| good | 4 | medium | low | low | low | 79to83 | america |
| good | 4 | low | low | medium | high | 79to83 | america |
| bad | 8 | high | high | high | low | 70to74 | america |
| good | 4 | low | medium | low | medium | 75to78 | europe |
| bad | 5 | medium | medium | medium | medium | 75to78 | europe |

Hypotheses: decision trees $f: X \rightarrow Y$

- Each internal node tests an attribute x_i
- Each branch
 assigns an
 attribute value x_i=v
- Each leaf assigns a class y
- To classify input x: traverse the tree from root to leaf, output the labeled y

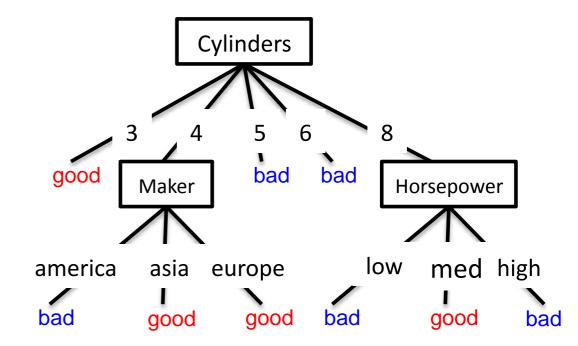


Human interpretable!

Hypothesis space

- How many possible hypotheses?
- What functions can be represented?

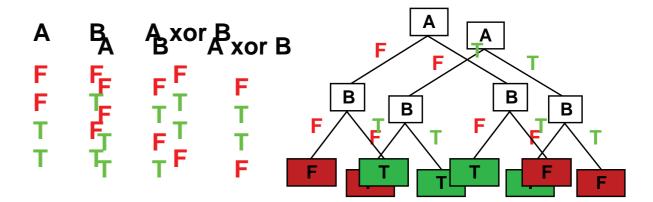
| mpg | cylinders | displacement | horsepower | weight | acceleration | modelyear | maker |
|------|-----------|--------------|------------|--------|--------------|-----------|---------|
| | | | | | | | |
| good | 4 | low | low | low | high | 75to78 | asia |
| bad | 6 | medium | medium | medium | medium | 70to74 | america |
| bad | 4 | medium | medium | medium | low | 75to78 | europe |
| bad | 8 | high | high | high | low | 70to74 | america |
| bad | 6 | medium | medium | medium | medium | 70to74 | america |
| bad | 4 | low | medium | low | medium | 70to74 | asia |
| bad | 4 | low | medium | low | low | 70to74 | asia |
| bad | 8 | high | high | high | low | 75to78 | america |
| : | : | | : | : | : | : | : |
| : | : | : | : | : | : | : | : |
| : | : | : | : | : | : | : | : |
| bad | 8 | high | high | high | low | 70to74 | america |
| good | 8 | high | medium | high | high | 79to83 | america |
| bad | 8 | high | high | high | low | 75to78 | america |
| good | 4 | low | low | low | low | 79to83 | america |
| bad | 6 | medium | medium | medium | high | 75to78 | america |
| good | 4 | medium | low | low | low | 79to83 | america |
| good | 4 | low | low | medium | high | 79to83 | america |
| bad | 8 | high | high | high | low | 70to74 | america |
| good | 4 | low | medium | low | medium | 75to78 | europe |
| bad | 5 | medium | medium | medium | medium | 75to78 | europe |



What functions can discrete the experience of the sented?

– E.g., for Boolean functions, truth table row \rightarrow path to lea

 Decision trees can represent any function of the input attributes!



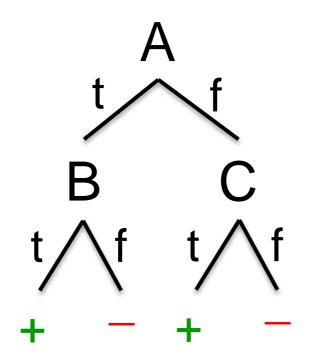
- For Boolean functions, Cpathous-input, continuous-output chiseure from Stuart Russell) to leaf gives truth table rowen approximate any function arbitrarily closely
- But, could require exponentially many nodes...

Trivially, there is a consistent where we will be a consistent where is a consistent where where where we will be a consistent where where where where where we will be a consistent with the consiste

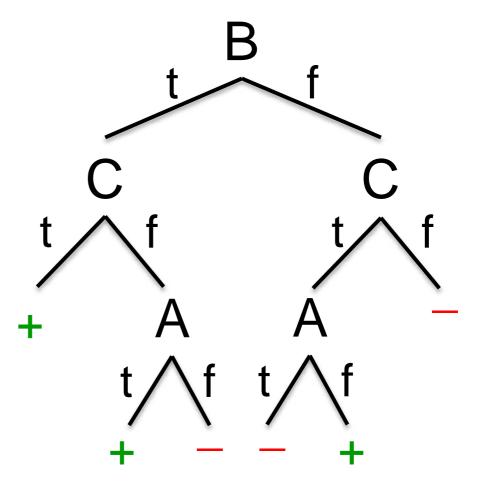
cyl=3 v (cyl=4 ^ (maker=asia v maker=europe)) v ...

Are all decision trees equal?

- Many trees can represent the same concept
- But, not all trees will have the same size
 - e.g., φ =(A \wedge B) \vee (\neg A \wedge C) ((A and B) or (not A and C))



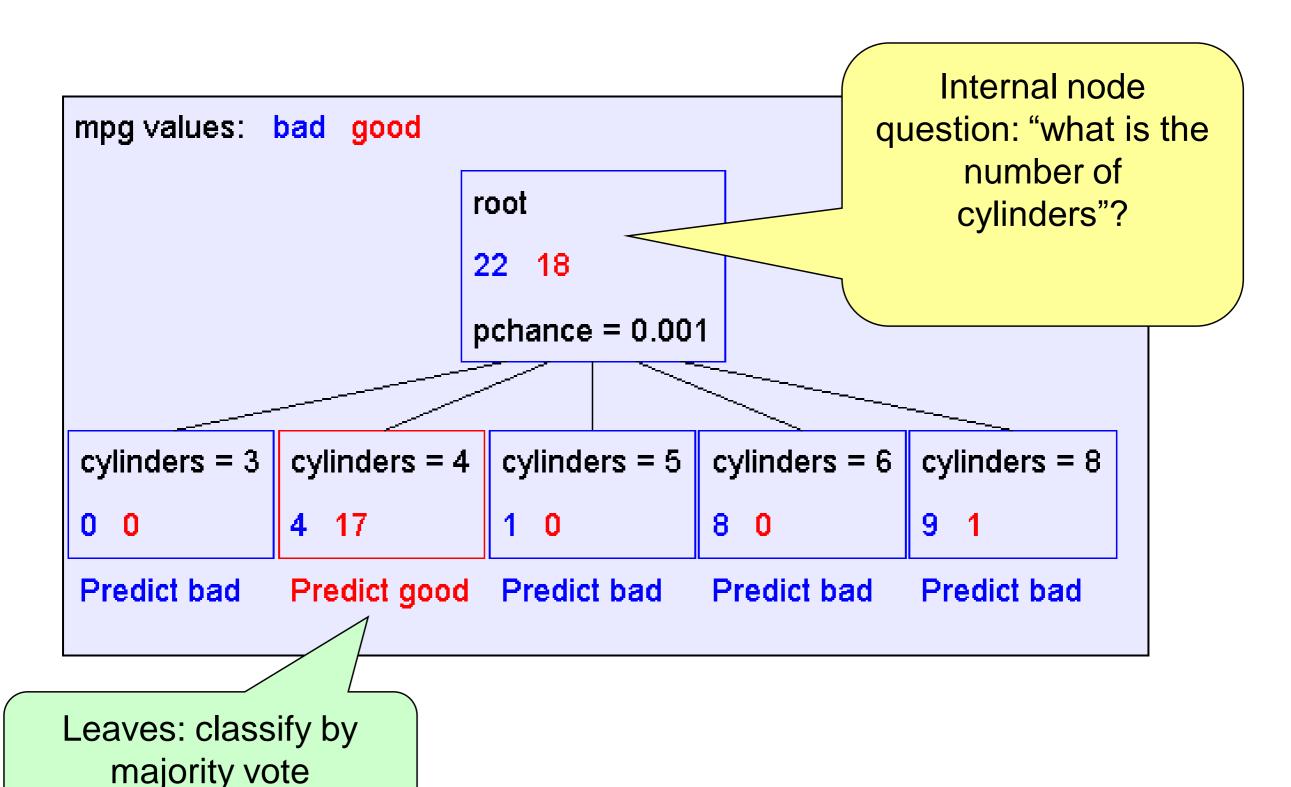
Which tree do we prefer?



Learning decision trees is hard!!!

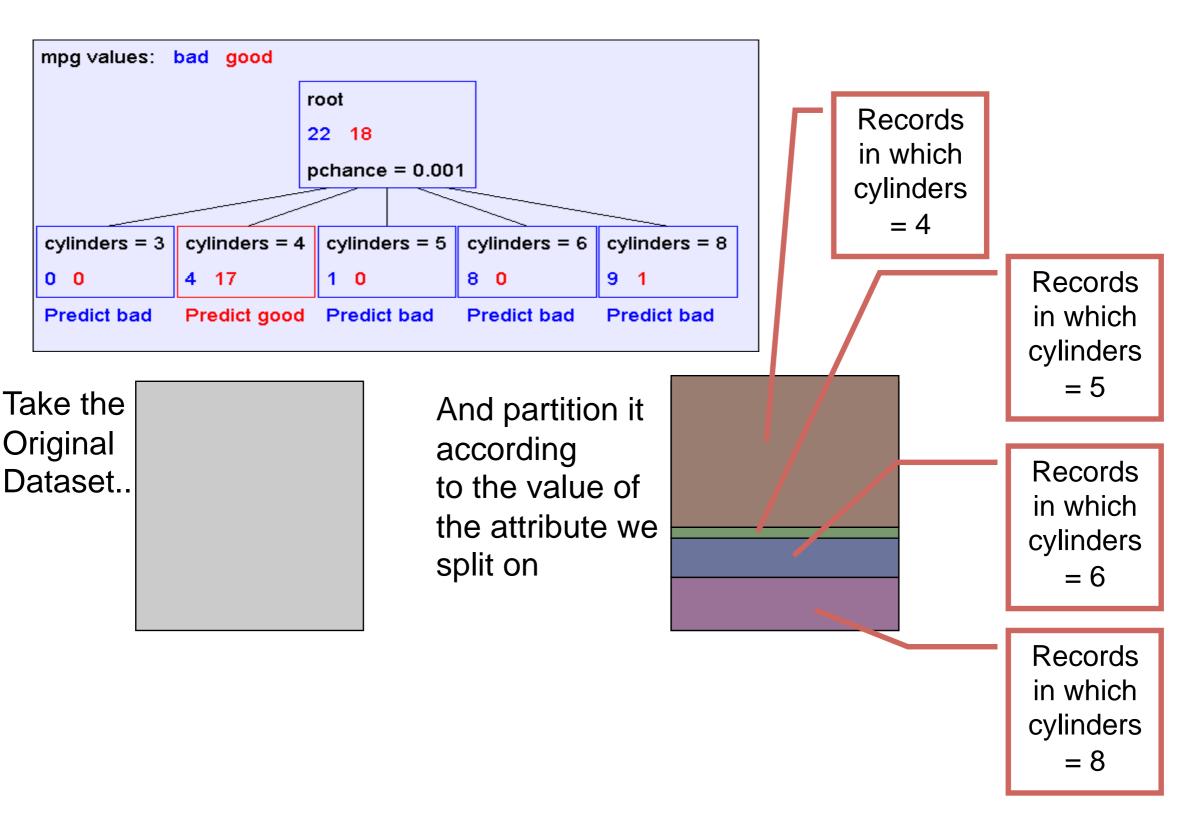
- Learning the simplest (smallest) decision tree is an NP-complete problem [Hyafil & Rivest '76]
- Resort to a greedy heuristic:
 - Start from empty decision tree
 - Split on next best attribute (feature)
 - Recurse

A Decision Stump

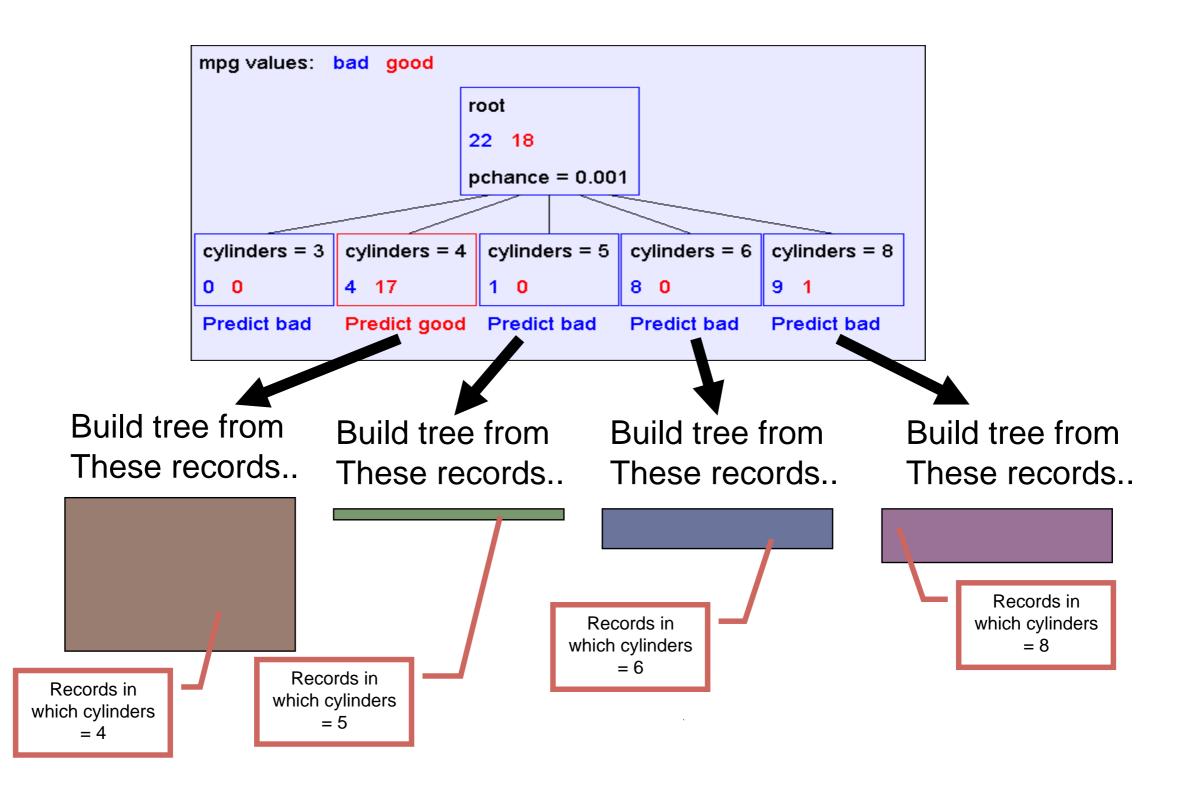


slide by Jerry Zhu

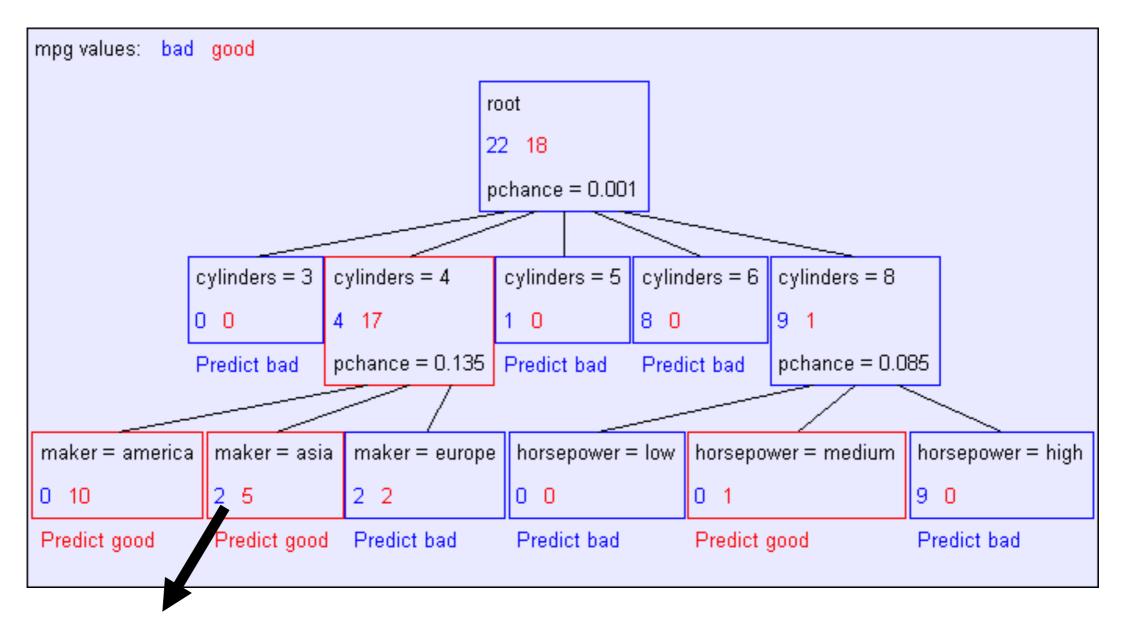
Key idea: Greedily learn trees using recursion



Recursive Step

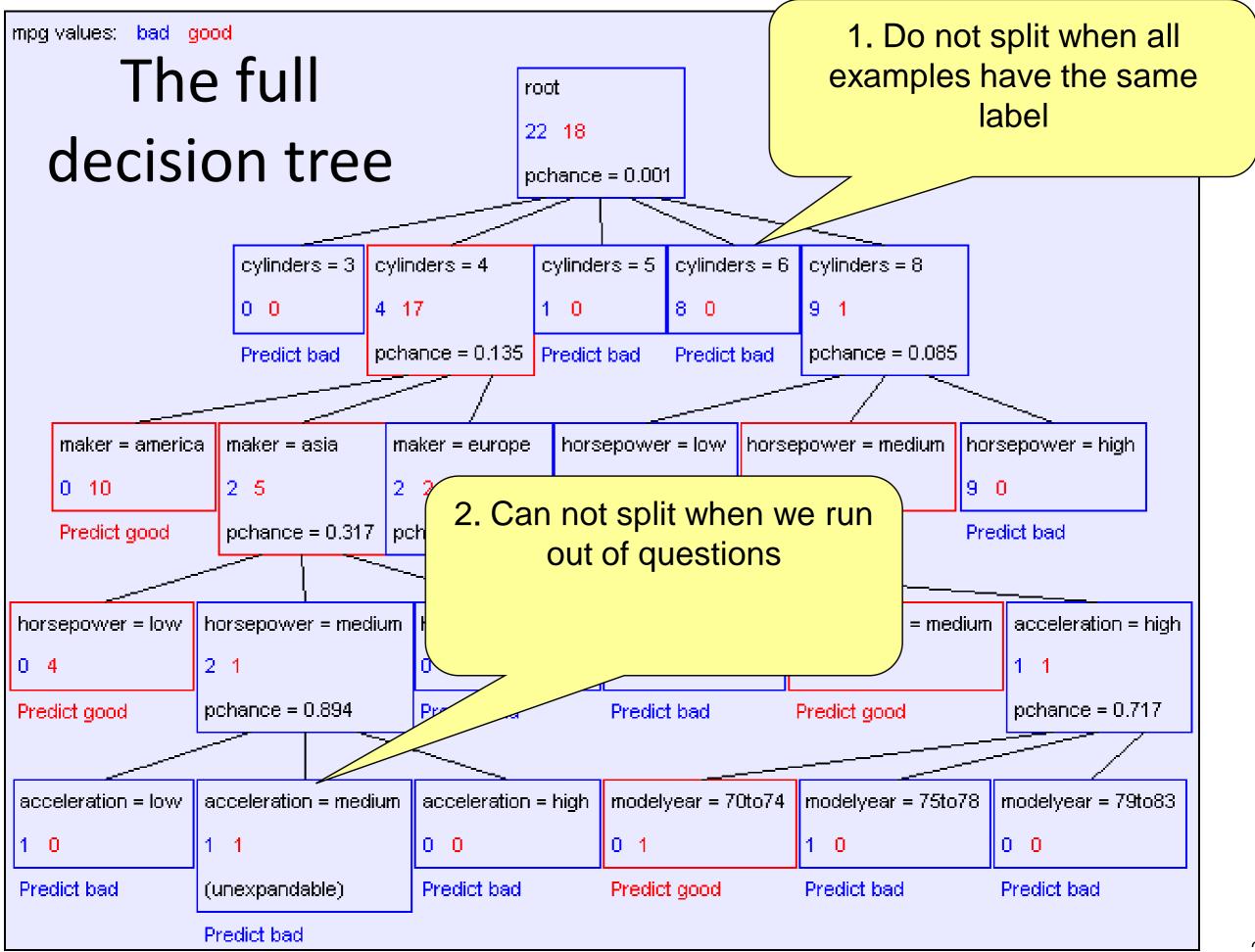


Second level of tree



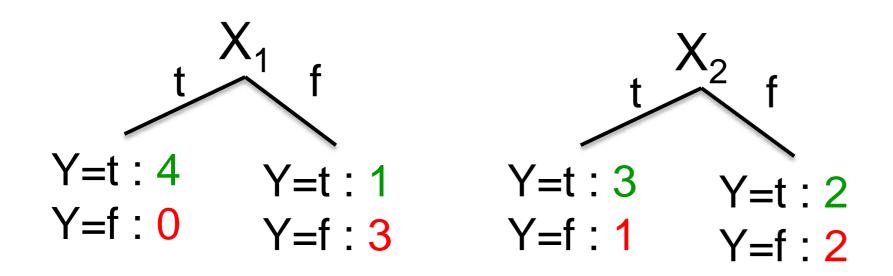
Recursively build a tree from the seven records in which there are four cylinders and the maker was based in Asia

(Similar recursion in the other cases)



Splitting: Choosing a good attribute

Would we prefer to split on X₁ or X₂?



Idea: use counts at leaves to define probability distributions, so we can measure uncertainty!

| | _ | _ |
|-------|-------|---|
| X_1 | X_2 | Y |
| Т | Т | Т |
| Τ | F | Т |
| Т | Т | Т |
| Т | F | Т |
| F | Т | Т |
| F | F | F |
| F | Т | F |
| F | F | F |

Measuring uncertainty

- Good split if we are more certain about classification after split
 - Deterministic good (all true or all false)
 - Uniform distribution bad
 - What about distributions in between?

| P(Y=A) = 1/2 | P(Y=B) = 1/4 | P(Y=C) = 1/8 | P(Y=D) = 1/8 |
|--------------|--------------|--------------|--------------|
|--------------|--------------|--------------|--------------|

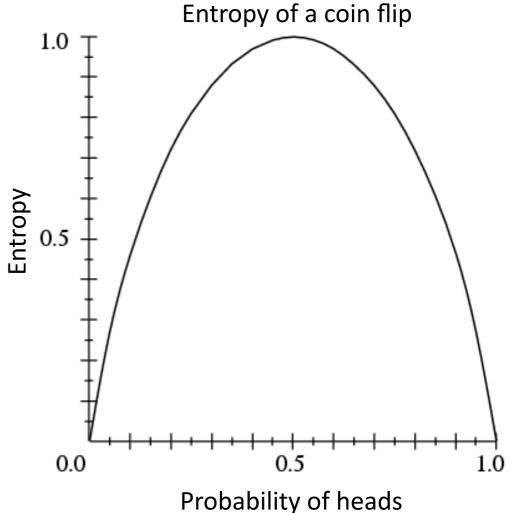
| P(Y=A) = 1/4 | P(Y=B) = 1/4 | P(Y=C) = 1/4 | P(Y=D) = 1/4 |
|--------------|--------------|--------------|--------------|
|--------------|--------------|--------------|--------------|

Entropy

Entropy H(Y) of a random variable Y

$$H(Y) = -\sum_{i=1}^{k} P(Y = y_i) \log_2 P(Y = y_i)$$

- More uncertainty, more entropy!
- Information Theory interpretation:
 H(Y) is the expected number of bits needed to encode a randomly drawn value of Y (under most efficient code)

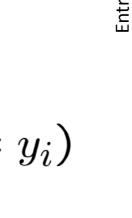


High, Low Entropy

- "High Entropy"
 - Y is from a uniform like distribution
 - Flat histogram
 - Values sampled from it are less predictable
- "Low Entropy"
 - Y is from a varied (peaks and valleys) distribution
 - Histogram has many lows and highs
 - Values sampled from it are more predictable

Entropy Example

$$H(Y) = -\sum_{i=1}^{k} P(Y = y_i) \log_2 P(Y = y_i)$$

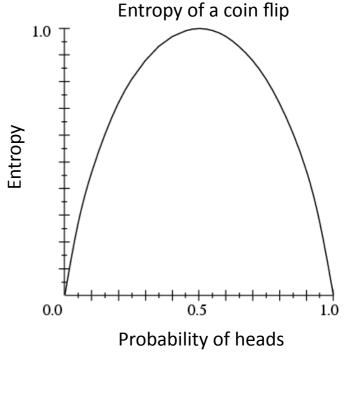


$$P(Y=t) = 5/6$$

$$P(Y=f) = 1/6$$

$$H(Y) = -5/6 \log_2 5/6 - 1/6 \log_2 1/6$$

= 0.65



| X ₁ | X_2 | Υ |
|----------------|-------|---|
| Т | Т | Т |
| Т | F | Т |
| Т | Т | Т |
| Т | F | Т |
| F | Т | Т |
| F | F | F |

Conditional Entropy

Conditional Entropy H(Y|X) of a random variable Y conditioned on a random variable X

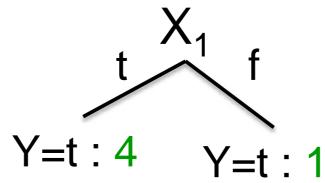
random variable
$$X$$

$$H(Y \mid X) = -\sum_{j=1}^{v} P(X = x_j) \sum_{i=1}^{k} P(Y = y_i \mid X = x_j) \log_2 P(Y = y_i \mid X = x_j)$$

Example:

$$P(X_1=t) = 4/6$$

$$P(X_1=f) = \frac{2}{6}$$



Y = 1 . 1 Y = 1 . 1Y = 1 . 1

$$H(Y|X_1) = -4/6 (1 \log_2 1 + 0 \log_2 0)$$
$$-2/6 (1/2 \log_2 1/2 + 1/2 \log_2 1/2)$$
$$= 2/6$$

| X ₁ | X_2 | Υ |
|----------------|-------|---|
| Т | Т | Т |
| Т | F | Т |
| Т | Т | Т |
| Т | F | Т |
| F | Т | Т |
| F | F | F |

Information gain

Decrease in entropy (uncertainty) after splitting

$$IG(X) = H(Y) - H(Y \mid X)$$

In our running example:

$$IG(X_1) = H(Y) - H(Y|X_1)$$

= 0.65 - 0.33

 $IG(X_1) > 0 \rightarrow$ we prefer the split!

| X ₁ | X_2 | Υ |
|----------------|-------|---|
| Τ | Т | Т |
| Т | F | Т |
| Т | Т | Т |
| Т | F | Т |
| F | Т | Т |
| F | F | F |

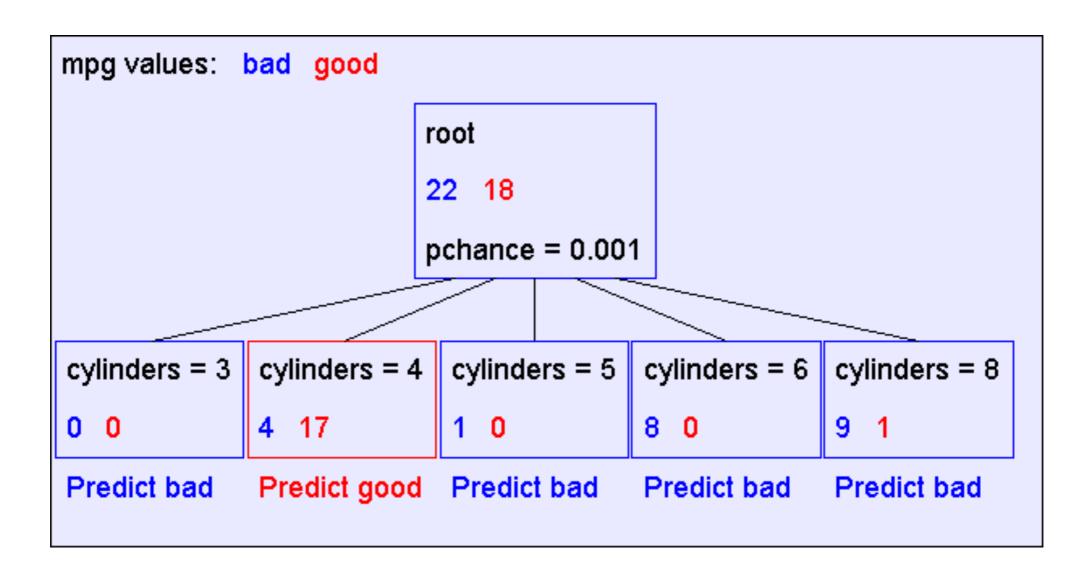
Learning decision trees

- Start from empty decision tree
- Split on next best attribute (feature)
 - Use, for example, information gain to select attribute:

$$\arg\max_i IG(X_i) = \arg\max_i H(Y) - H(Y \mid X_i)$$

Recurse

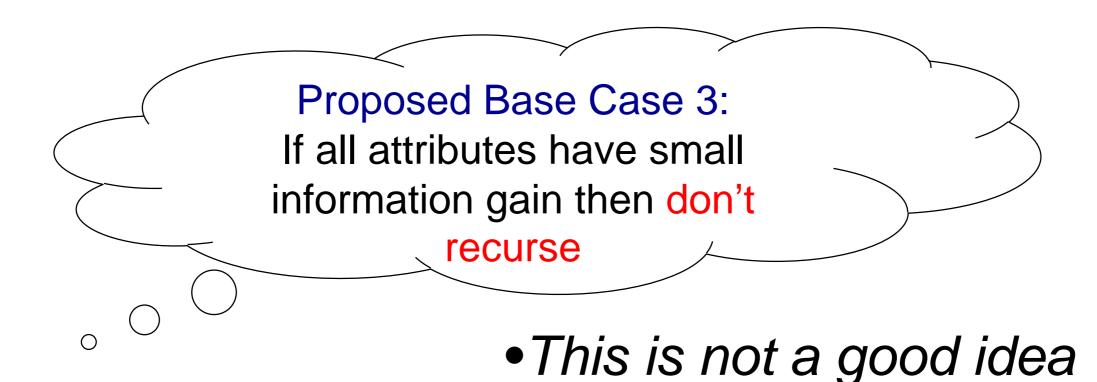
When to stop?



 First split looks good! But, when do we stop?

Base Cases: An idea

- Base Case One: If all records in current data subset have the same output then don't recurse
- Base Case Two: If all records have exactly the same set of input attributes then don't recurse

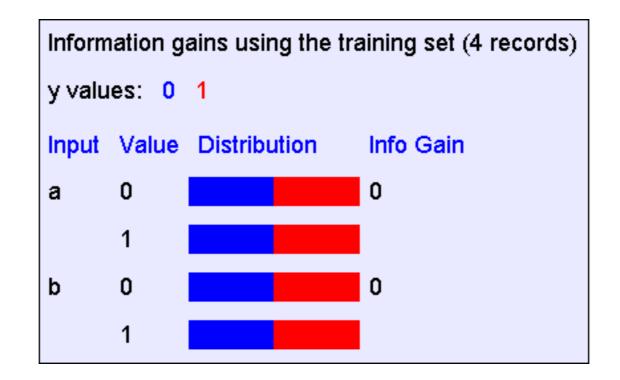


The problem with proposed case 3

$$y = a XOR b$$

| а | b | у |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

The information gains:



If we omit proposed case 3:

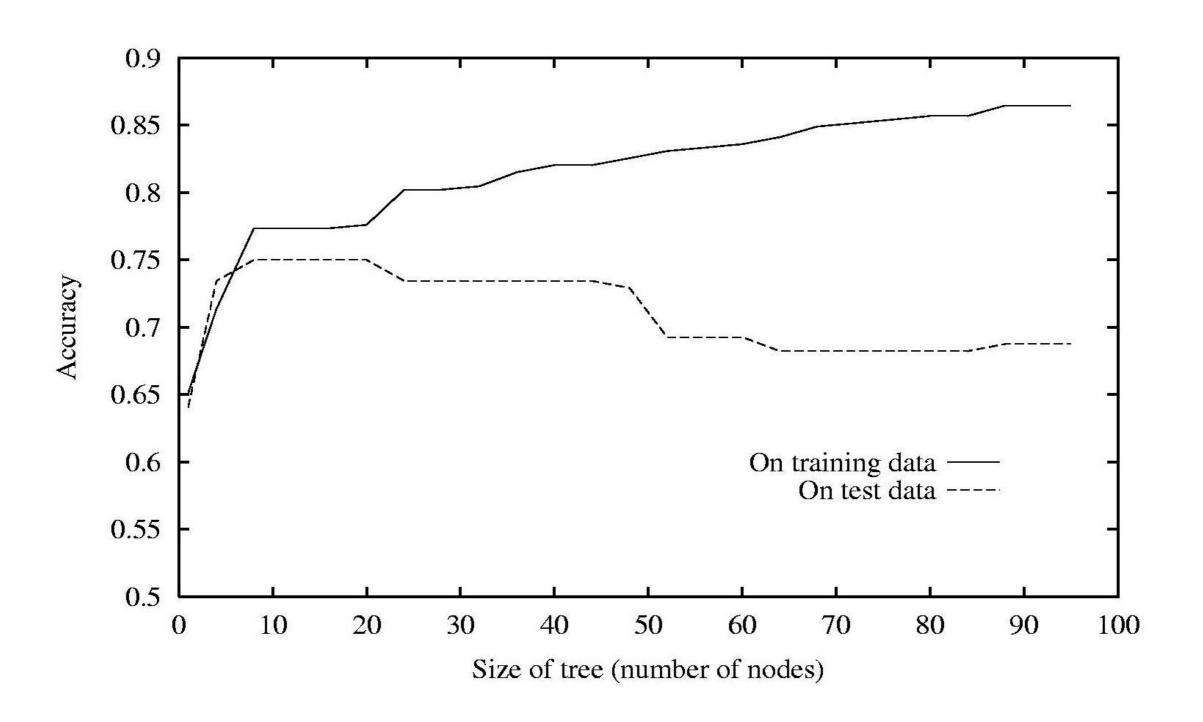
| а | b | у |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

Instead, perform **pruning** after building a tree

The resulting decision tree:

```
y values: 0 1
            root
            pchance = 1.000
   a = 0
                     a = 1
   pchance = 0.414
                     pchance = 0.414
b = 0
           b = 1
                     b = 0
                                b = 1
  -0
                                1 0
Predict 0 Predict 1
                     Predict 1
                                Predict 0
```

Decision trees will overfit



Decision trees will overfit

- Standard decision trees have no learning bias
 - Training set error is always zero!
 - · (If there is no label noise)
 - Lots of variance
 - Must introduce some bias towards simpler trees
- Many strategies for picking simpler trees
 - Fixed depth
 - Fixed number of leaves

Random forests

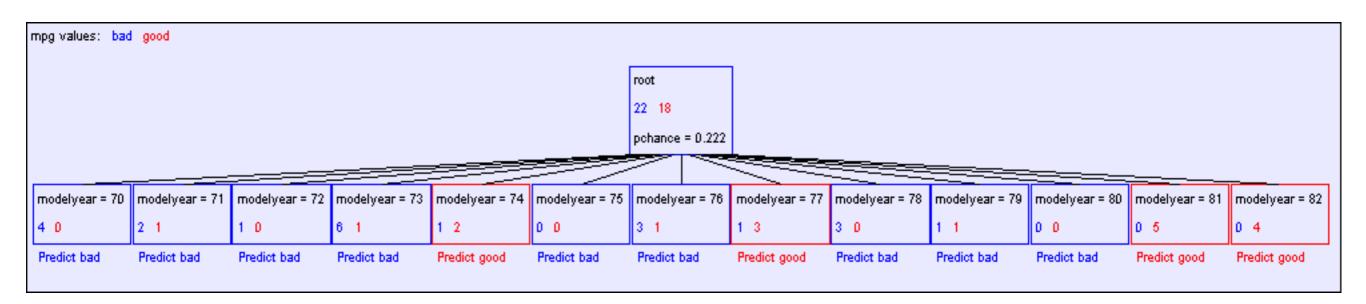
Real-valued inputs

What should we do if some of the inputs are real-valued?

Infinite number of possible split values!!!

| mpg | cylinders | displacemen | horsepower | weight | acceleration | modelyear | maker |
|------|-----------|-------------|------------|--------|--------------|-----------|---------|
| | | | | | | | |
| good | 4 | 97 | 75 | 2265 | 18.2 | 77 | asia |
| bad | 6 | 199 | 90 | 2648 | 15 | 70 | america |
| bad | 4 | 121 | 110 | 2600 | 12.8 | 77 | europe |
| bad | 8 | 350 | 175 | 4100 | 13 | 73 | america |
| bad | 6 | 198 | 95 | 3102 | 16.5 | 74 | america |
| bad | 4 | 108 | 94 | 2379 | 16.5 | 73 | asia |
| bad | 4 | 113 | 95 | 2228 | 14 | 71 | asia |
| bad | 8 | 302 | 139 | 3570 | 12.8 | 78 | america |
| : | : | : | : | : | : | : | : |
| : | : | : | : | : | : | : | : |
| : | : | : | : | : | : | : | : |
| good | 4 | 120 | 79 | 2625 | 18.6 | 82 | america |
| bad | 8 | 455 | 225 | 4425 | 10 | 70 | america |
| good | 4 | 107 | 86 | 2464 | 15.5 | 76 | europe |
| bad | 5 | 131 | 103 | 2830 | 15.9 | 78 | europe |
| | | | | | | | |

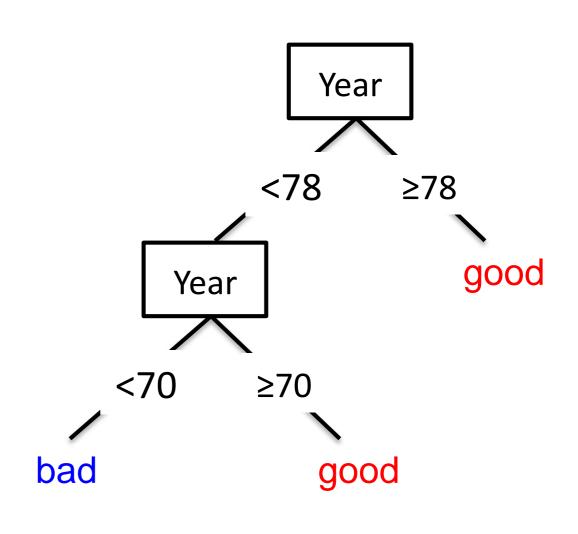
"One branch for each numeric value" idea:



Hopeless: hypothesis with such a high branching factor will shatter any dataset and overfit

Threshold splits

- Binary tree: split on attribute X at value t
 - One branch: X < t
 - Other branch: X ≥ t
- Requires small change
 - Allow repeated splits on same variable along a path



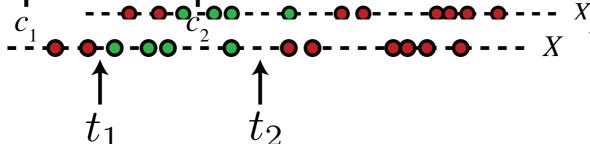
The set of possible thresholds

- Binary tree, split on attribute X
 - One branch: X < t
 - Other parametrist for continuous attributes
- Search through possible values of t Infinitely many possible split points c to define node test $X_j > c$?
 - Seems hard!!!
- No! Moving split point along the empty space between two observed values UI ONLY a finite number of the empty space between two observed values has no effect on information gain or empirical loss; so just use midpoint infinitely many possible split points c to define hode test $X_j > c$?

No! Moving split point along the empty space between two observed values has no effect on information gain of empirical loss; so just use midpoint

- · Sort data according to This is a series of the series of
- Consider sphilipoints of the plot from different chases.

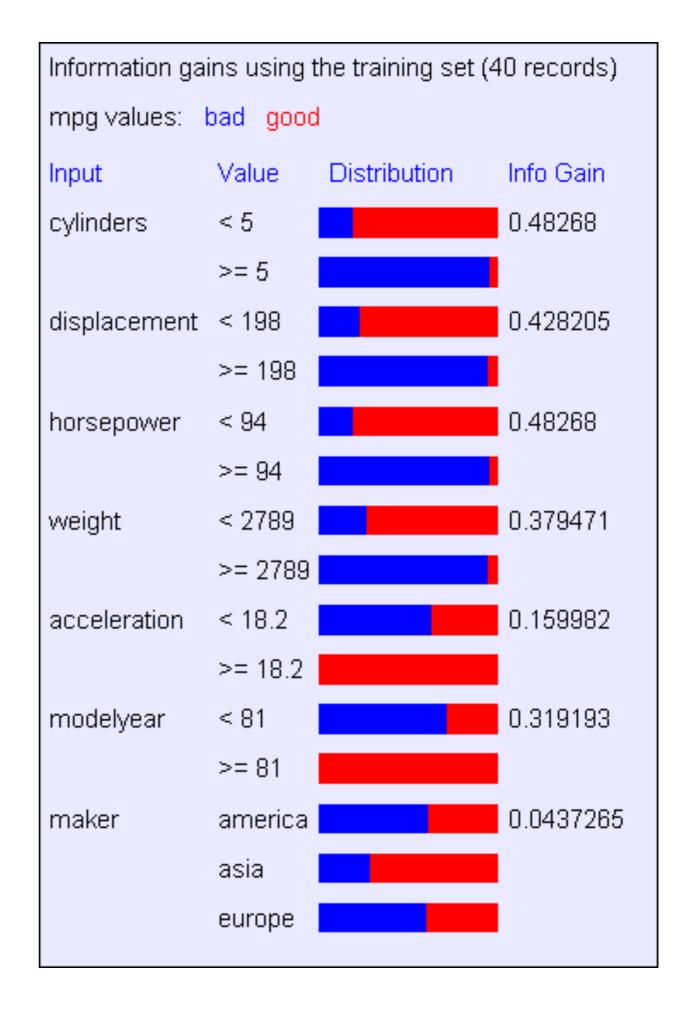
 Consider sphilipoints of the plot from different chases.
 - classes matter optimal for information gain or empirical loss reduction



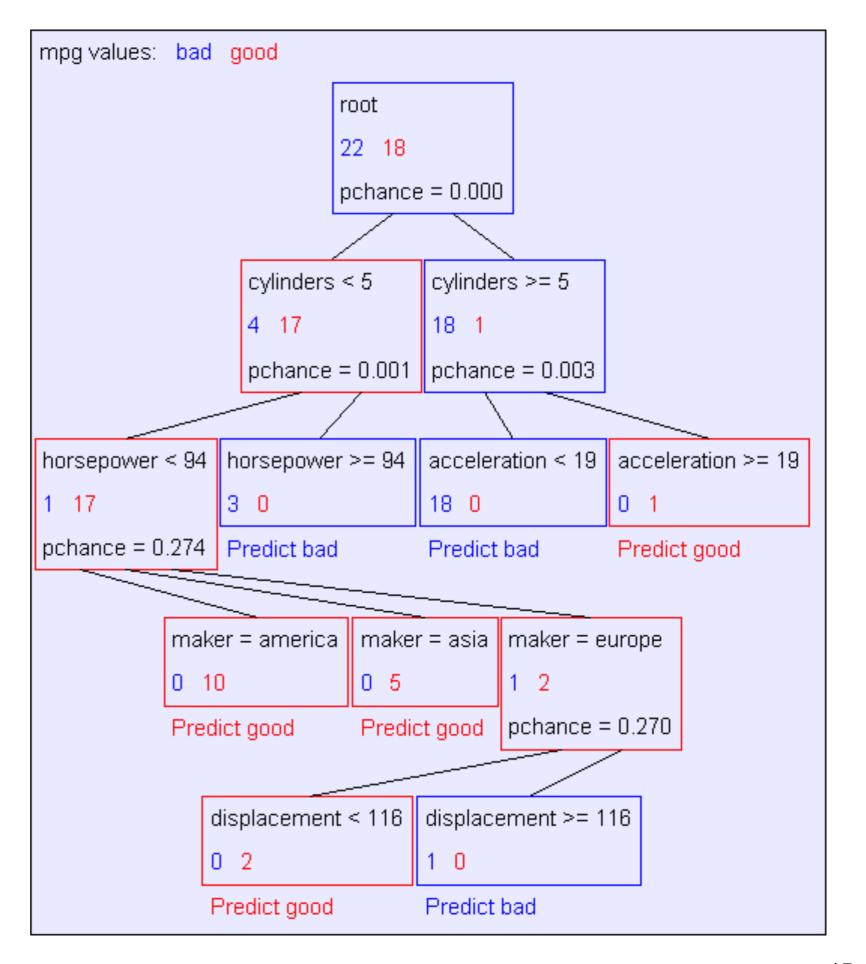
Picking the best threshold

- Suppose X is real valued with threshold t
- Want IG(Y|X:t), the information gain for Y when testing if X is greater than or less than t
- Define:
 - H(Y | X:t) = p(X<t)H(Y | X<t)+p(X>=t)H(Y | X>=t)
 - IG(Y | X:t) = H(Y) H(Y | X:t)
 - $IG^*(Y | X) = \max_t IG(Y | X:t)$
- Use: $IG^*(Y | X)$ for continuous variables

Example with MPG



Example tree for our continuous dataset



Demo time...

What you need to know about decision trees

- Decision trees are one of the most popular ML tools
 - Easy to understand, implement, and use
 - Computationally cheap (to solve heuristically)
- Information gain to select attributes (ID3, C4.5,...)
- Presented for classification, can be used for regression and density estimation too
- Decision trees will overfit!!!
 - Must use tricks to find "simple trees", e.g.,
 - Fixed depth/Early stopping
 - Pruning
 - Or, use ensembles of different trees (random forests)

slide by Vibhav Gog

Decision Trees vs SVM

| Characteristic | SVM | Trees |
|--|----------|--------------|
| Natural handling of data of "mixed" type | • | A |
| Handling of missing values | • | A |
| Robustness to outliers in input space | • | |
| Insensitive to monotone transformations of inputs | • | |
| Computational scalability (large N) | • | |
| Ability to deal with irrelevant inputs | _ | A |
| Ability to extract linear combinations of features | A | V |
| Interpretability | _ | \(\) |
| Predictive power | _ | • |